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Inter-University Research Institute Corporation / Research Organization of Information and Systems

#### National Institute of Informatics

# Machine Learning and Information Geometry II

Introduction to Intelligent Systems Science II

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#### **Various Hierarchical Models as Posets**



# **Pattern Mining**



#### **Frequency as Importance Measure**



#### **Probability on Poset**



#### Pattern Mining → Upward Analysis



#### **Boltzmann Machines**



#### **Boltzmann Machines** → **Downward Analysis**



#### Pattern Mining & Boltzmann Machines



### **Partially Ordered Set**



- Partially ordered set (poset) (S, ≤)
  - (i)  $x \le x$  (reflexivity)
  - (ii)  $x \le y, y \le x \Rightarrow x = y$  (antisymmetry)
  - (iii)  $x \le y, y \le z \Rightarrow x \le z$  (transitivity)
    - We assume that S is finite and includes the least element (bottom)  $\perp \in S$
- Equivalent to a DAG
  - Each  $x \in S$  is a node
  - $x \le y \iff y$  is reachable from x

# Log-Linear Model on Poset



- A probability vector  $p: S \rightarrow (0, 1)$ s.t.  $\sum_{x \in S} p(x) = 1$ 
  - (Normalized) weight for each node
- We introduce  $\theta: S \to \mathbb{R}$  and  $\eta: S \to \mathbb{R}$  as  $\theta(x) = \sum_{s \in S} \mu(s, x) \log p(s), \ \eta(x) = \sum_{s \ge x} p(s)$
- From the Möbius inversion formula:  $\log p(x) = \sum_{s \le x} \theta(s), \ p(x) = \sum_{s \in S} \mu(x, s) \eta(s)$ 10/34

#### **Möbius Function on Poset**



• Zeta function 
$$\zeta: S \times S \rightarrow \{0, 1\}$$
  
 $\zeta(s, x) = \begin{cases} 1 & \text{if } s \leq x, \\ 0 & \text{otherwise.} \end{cases}$ 

Möbius function 
$$\mu: S \times S \rightarrow \mathbb{Z}$$
 $\mu(x, y) = \begin{cases} 1 & \text{if } x = y, \\ -\sum_{x \le s < y} \mu(x, s) & \text{if } x < y, \\ 0 & \text{otherwise} \end{cases}$ 

– We have  $\zeta \mu = I$  (convolutional inverse):

$$\sum_{s \in S} \zeta(s, y) \mu(x, s) = \sum_{x \le s \le y} \mu(x, s) = \delta_{xy}$$
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#### **Dually Flat Structure**

- $\theta$  and  $\eta$  form a dual coordinate system:
  - $\nabla \psi(\theta) = \eta, \ \nabla \varphi(\eta) = \theta$ 
    - $\psi(\theta) = -\theta(\bot) = -\log p(\bot), \ \varphi(\eta) = \sum_{x \in S} p(x) \log p(x)$
    - $\psi(\theta)$  and  $\varphi(\eta)$  are connected via the Legendre transformation:  $\varphi(\eta) = \max_{\theta'} \left( \theta' \eta - \psi(\theta') \right), \quad \theta' \eta = \sum_{x \in S \setminus \{\bot\}} \theta'(x) \eta(x)$

•  $\psi(\theta)$  and  $\varphi(\eta)$  should be convex

#### **Gradient and Riemannian Manifold**

• The gradients:  $g(\theta) = \nabla \nabla \psi(\theta) = \nabla \eta$ ,  $g(\eta) = \nabla \nabla \varphi(\eta) = \nabla \theta$ 

$$\begin{cases} g_{xy}(\theta) = \frac{\partial \eta(x)}{\partial \theta(y)} = \sum_{s \in S} \zeta(x, s)\zeta(y, s)p(s) - \eta(x)\eta(y) \\ g_{xy}(\eta) = \frac{\partial \theta(x)}{\partial \eta(y)} = \sum_{s \in S} \mu(s, x)\mu(s, y)p(s)^{-1} \end{cases}$$

- ζ and μ are the zeta function and the Möbius function determined by the partial order (DAG) structure
- The manifold (S,  $g(\xi)$ ) is a Riemannian manifold with the set S of probability vectors and the Riemannian metric  $g(\xi) = 13/34$

# **Fisher Information Matrix and Orthogonality**

• Since  $g(\xi)$  coincides with the Fisher information matrix,

$$\mathbf{E}\left[\frac{\partial}{\partial\theta(x)}\log p(s)\frac{\partial}{\partial\theta(y)}\log p(s)\right] = g_{xy}(\theta),$$
$$\mathbf{E}\left[\frac{\partial}{\partial\eta(x)}\log p(s)\frac{\partial}{\partial\eta(y)}\log p(s)\right] = g_{xy}(\eta)$$

•  $\theta$  and  $\eta$  are orthogonal, i.e.,

$$\mathbf{E}\left[\frac{\partial}{\partial\theta(x)}\log p(s)\frac{\partial}{\partial\eta(y)}\log p(s)\right] = \sum_{s\in S}\zeta(x,s)\mu(s,y) = \delta_{xy}$$

#### e-Projection and m-Projection



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#### Computation of *e*-Projection

• Given *P* and  $\beta$ , we compute  $P_{\beta}$  such that

$$\begin{cases} \theta_{P_{\beta}}(x) = \theta_{P}(x) & \text{if } x \in (S \setminus \{\bot\}) \setminus \text{dom}(\beta), \\ \eta_{P_{\beta}}(x) = \beta(x) & \text{if } x \in \text{dom}(\beta) \end{cases}$$

• Initialize with 
$$P_{\beta}^{(o)} = P$$
 and, at each step  $t$ ,  
update  $\eta_{P_{\beta}}^{(t)}(x)$  for  $x \in \text{dom}(\beta)$ 

- Since  $\theta$  and  $\eta$  are orthogonal, we can change  $\eta_{P_{\beta}}^{(t)}(x)$ while fixing  $\theta_{P_{\beta}}^{(t)}(y)$  for  $y \notin \text{dom}(\beta)$ 

## Gradient

- We can use Newton's method as we can compute the derivatives  $\partial \theta^{(t)}(x) / \partial \eta^{(t)}(y)$  and  $\partial \eta^{(t)}(x) / \partial \theta^{(t)}(y)$ , thanks to the Möbius inversion
- Gradient of  $\theta$  and  $\eta$  is obtained as the Riemannian metric:  $g(\theta) = \nabla \nabla \psi(\theta) = \nabla \eta$  and  $g(\eta) = \nabla \nabla \varphi(\eta) = \nabla \theta$   $\frac{\partial \eta(x)}{\partial \theta(y)} = \sum_{s \in S} \zeta(x, s)\zeta(y, s)p(s) - \eta(x)\eta(y),$  $\frac{\partial \theta(x)}{\partial \eta(y)} = \sum_{s \in S} \mu(s, x)\mu(s, y)p(s)^{-1}$

# Newton's Method (1/2)

• Each step of Newton's method:

$$\begin{bmatrix} \eta_{P_{\beta}}^{(t)}(x) - \beta(x) \\ \vdots \end{bmatrix} + J \begin{bmatrix} \vdots \\ \theta_{P_{\beta}}^{(t+1)}(y) - \theta_{P_{\beta}}^{(t)}(y) \\ \vdots \end{bmatrix} = \mathbf{o},$$

- J is the  $|dom(\beta)| \times |dom(\beta)|$  Jacobian matrix given as

$$J_{xy} = \frac{\partial \eta_{P_{\beta}}^{(t)}(x)}{\partial \theta_{P_{\beta}}^{(t)}(y)} = \sum_{s \in S} \zeta(x, s) \zeta(y, s) p_{\beta}^{(t)}(s) - \eta_{P_{\beta}}^{(t)}(x) \eta_{P_{\beta}}^{(t)}(y)$$
  
for each  $x, y \in \text{dom}(\beta)$ 

# Newton's Method (2/2)

• Each update is

$$\begin{bmatrix} \theta_{P_{\beta}}^{(t+1)}(x) \\ \vdots \\ \vdots \end{bmatrix} = \begin{bmatrix} \theta_{P_{\beta}}^{(t)}(x) \\ \vdots \\ \vdots \end{bmatrix} - J^{-1} \begin{bmatrix} \vdots \\ \eta_{P_{\beta}}^{(t)}(y) - \beta(y) \\ \vdots \end{bmatrix}$$

- $J^{-1}$  is the inverse of J
- J is the  $|dom(\beta)| \times |dom(\beta)|$  Jacobian matrix given as

$$J_{xy} = \frac{\partial \eta_{P_{\beta}}^{(t)}(x)}{\partial \theta_{P_{\beta}}^{(t)}(y)} = \sum_{s \in S} \zeta(x, s) \zeta(y, s) p_{\beta}^{(t)}(s) - \eta_{P_{\beta}}^{(t)}(x) \eta_{P_{\beta}}^{(t)}(y)$$

for each  $x, y \in dom(\beta)$ 

#### **CP** Decomposition

- Approximate a tensor  $\mathcal{X}$  by R rank-1 tensors:  $x_{ijk} \approx \sum_{r=1}^{R} u_{ir} v_{jr} w_{kr}$ 
  - Number of parameters  $IJK \rightarrow R(I + J + K)$



#### **Tucker Decomposition**

- Approximate a tensor  $\mathcal{X}$  by three matrices and a core tensor:  $x_{ijk} \approx \sum_{r=1}^{R} \sum_{s=1}^{S} \sum_{t=1}^{T} c_{rst} u_{ir} v_{js} w_{kt}$ 
  - Number of parameters  $IJK \rightarrow RST + IR + JS + KT$



#### From Matrix to Poset (DAG)



#### Input matrix:



















#### Information Geometry



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#### **Information Geometry**



# **Summary of Lectrue**

- Information geometric formulation connects
   pattern mining and Boltzmann machines
  - Applications including matrix balancing
  - Sugiyama, M., Nakahara, H., Tsuda, K.:
     Tensor Balancing on Statistical Manifold, ICML 2017
- Discrete structure (posets) + Information Geometry = Strong formulation for data analysis!
- Further application to tensor decomposition:
  - Sugiyama, M., Nakahara, H., Tsuda, K.:
     Legendre Decomposition for Tensors, NeurIPS 2018