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Inter-University Research Institute Corporation /
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National Institute of Informatics

Bias-Variance Tradeoff

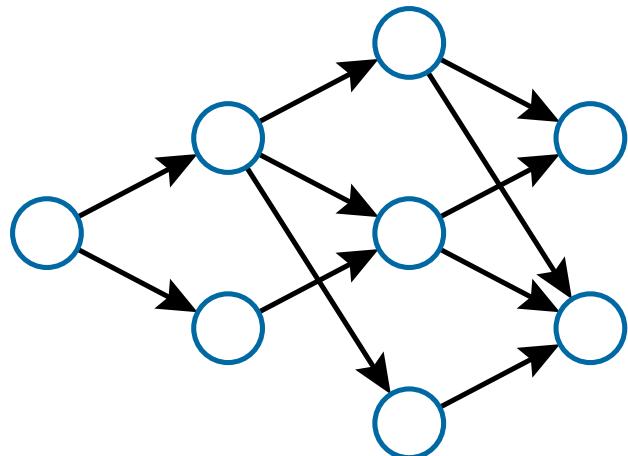
Data Mining 06 (データマイニング)

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Today's Outline

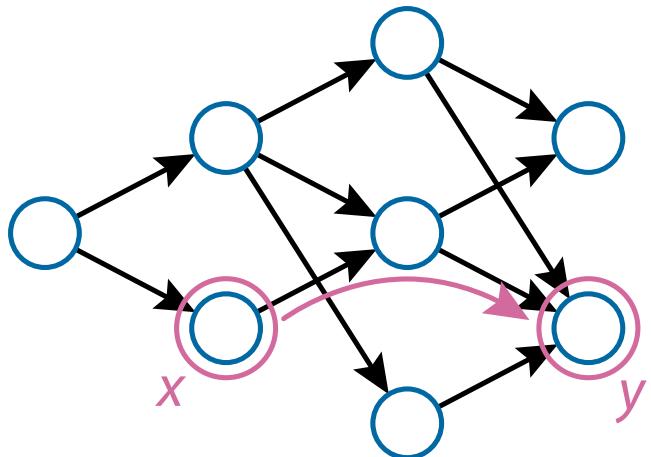
- Log-linear models on posets
 - A generalized formulation of Boltzmann machines
- Bias-variance tradeoff
- Fisher information & Cramér-Rao inequality

Partially Ordered Set (Poset)



- Partially ordered set (**poset**) (S, \leq)
 - (i) $x \leq x$ (reflexivity)
 - (ii) $x \leq y, y \leq x \Rightarrow x = y$ (antisymmetry)
 - (iii) $x \leq y, y \leq z \Rightarrow x \leq z$ (transitivity)
- We assume that S is finite and includes the least element (bottom) $\perp \in S$

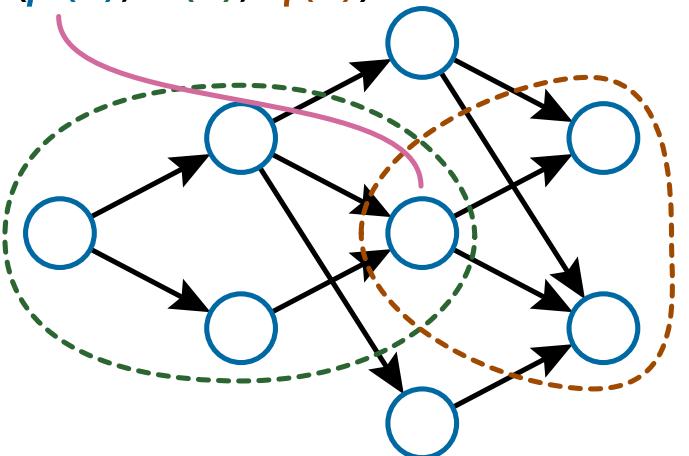
Partially Ordered Set



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 - We assume that S is finite and includes the least element (bottom) $\perp \in S$
- Equivalent to a DAG
 - Each $x \in S$ is a node
 - $x \leq y \iff y$ is reachable from x

Log-Linear Model on Poset

Each $x \in S$ has a triple:
 $(p(x), \theta(x), \eta(x))$



- A probability distribution $p:S \rightarrow (0, 1)$
s.t. $\sum_{x \in S} p(x) = 1$
- We introduce $\theta:S \rightarrow \mathbb{R}$ and $\eta:S \rightarrow \mathbb{R}$ as
$$\log p(x) = \sum_{s \leq x} \theta(s)$$
$$\eta(x) = \sum_{s \geq x} p(s)$$
 - Parameter set $B \subseteq S$
 - $\theta(s) = 0$ if $s \notin B$

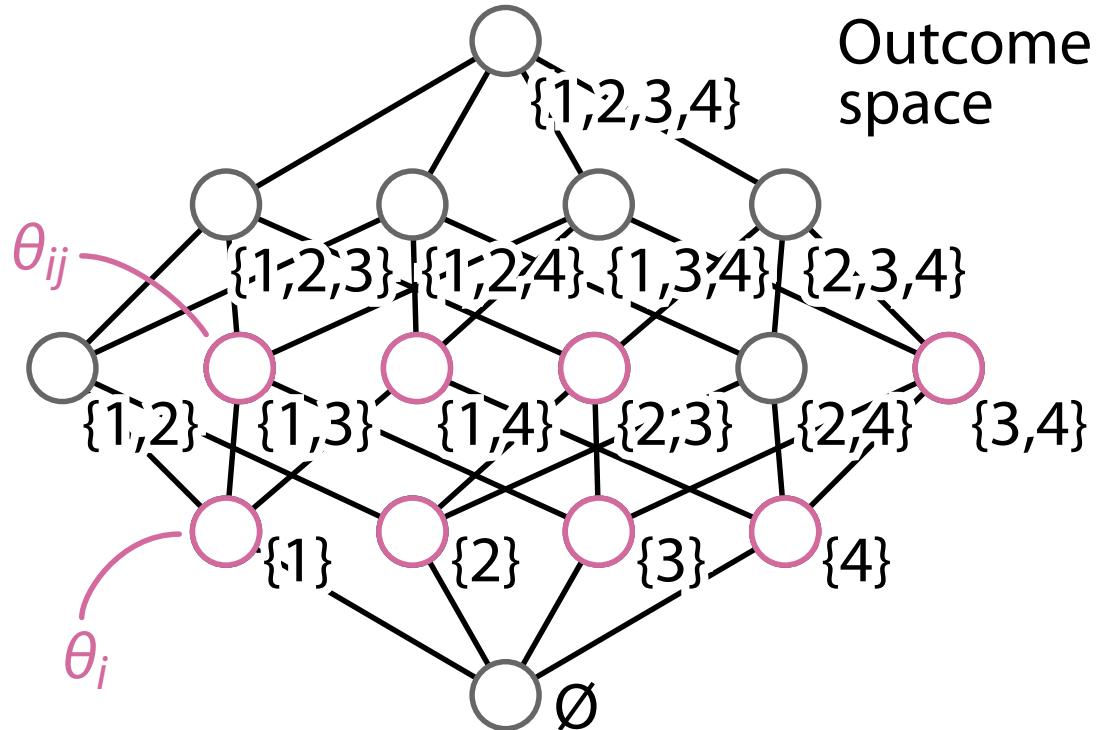
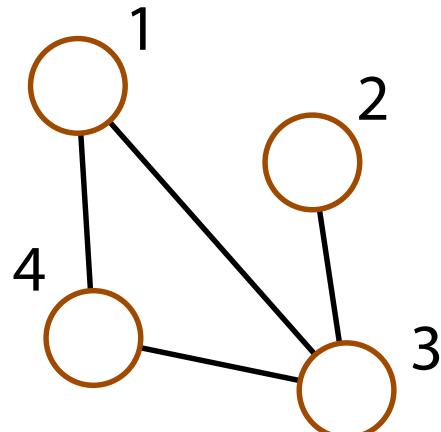
Log-Linear Model on Powerset

- Probability distribution over the power set 2^V with $V = \{1, 2, \dots, n\}$
 - $x \leq y \iff x \subseteq y, S = 2^V$
- Probability $p(x)$ for each $x \in 2^V$ is given as $\log p(x) = \sum_{s \subseteq x} \theta(s)$
 - Parameter set $B \subseteq 2^V$
 - $\theta(s) = 0$ if $s \notin B$
- **MLE:** Find $\theta(s)$ from a dataset $D \subseteq 2^V$ for all $s \in B$ s.t. $\eta(s) = \hat{\eta}(s)$

$$\eta(s) = \sum_{x \supseteq s} p(x), \quad \hat{\eta}(s) = \frac{1}{|D|} \sum_{x \in D} \mathbf{1}[x \supseteq s] = |\{x \in D \mid x \supseteq s\}| / |D|$$

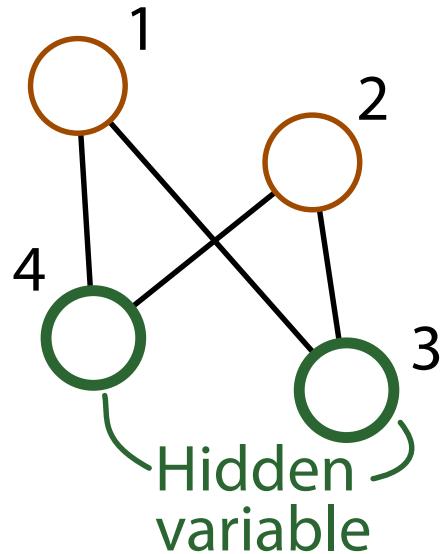
Boltzmann Machines

Boltzmann
Machine (BM)

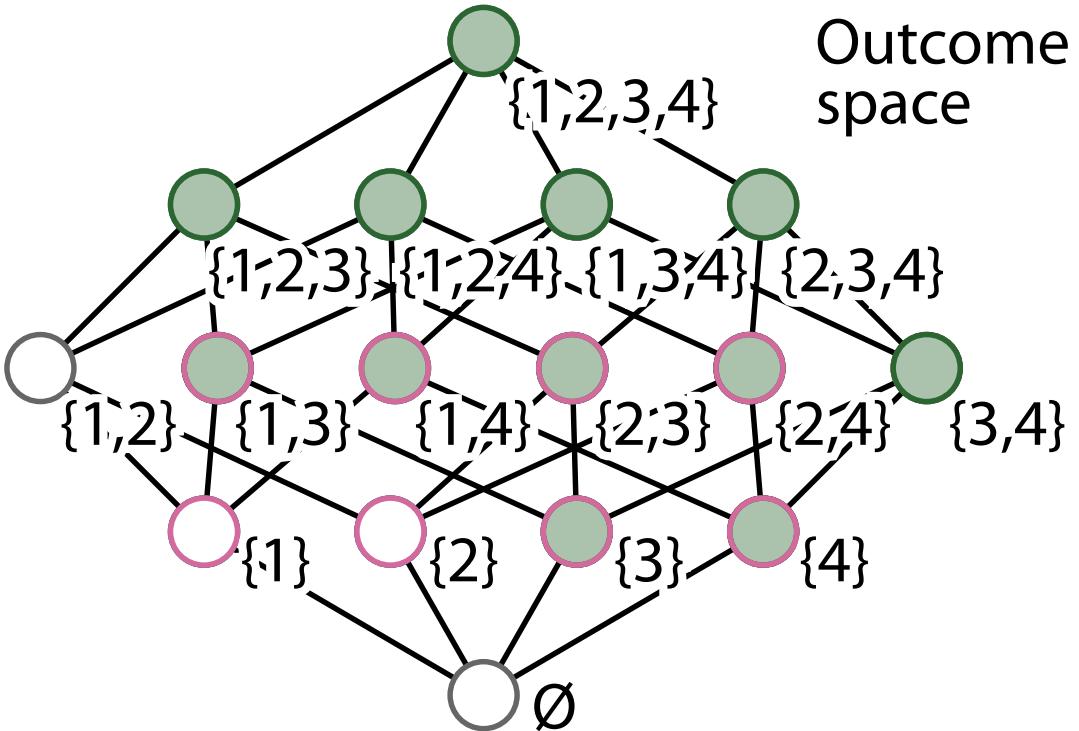


Restricted Boltzmann Machines (RBMs)

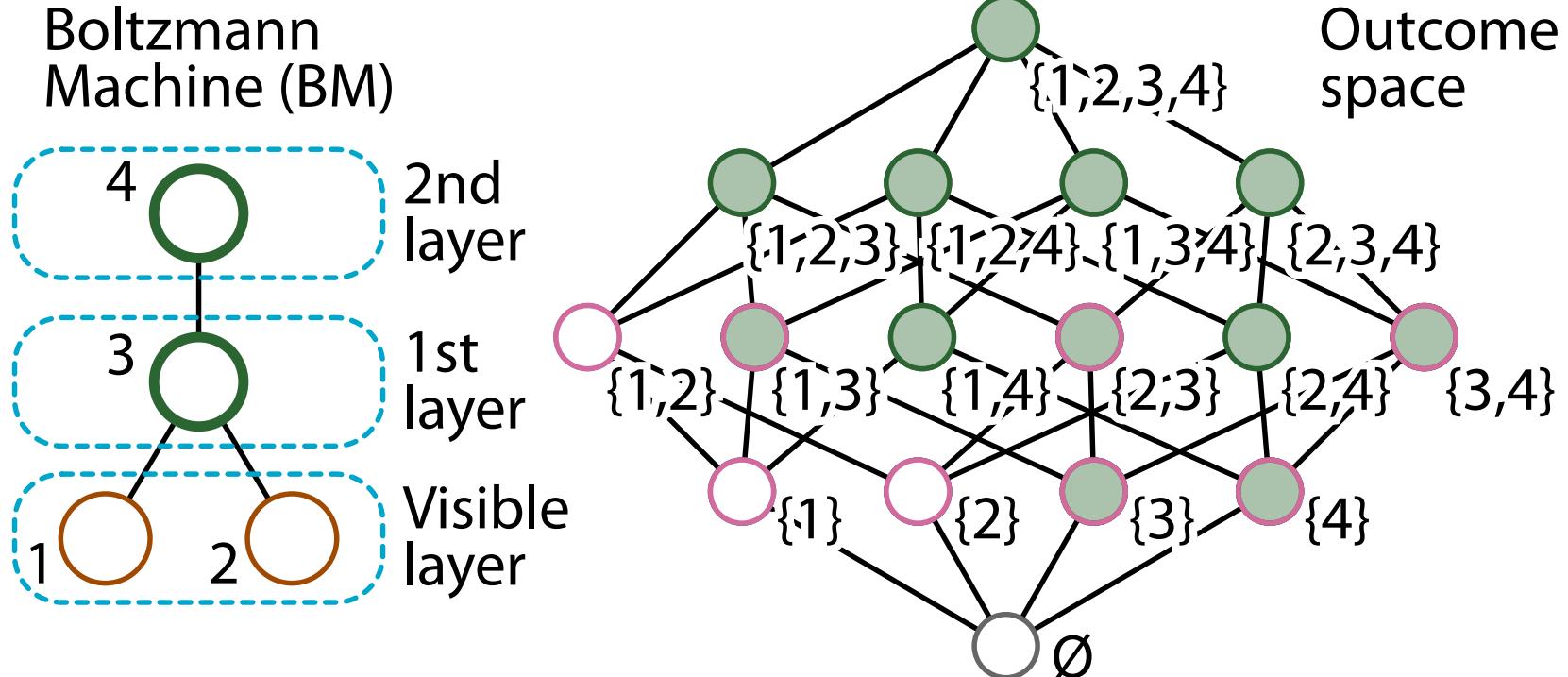
Boltzmann
Machine (BM)



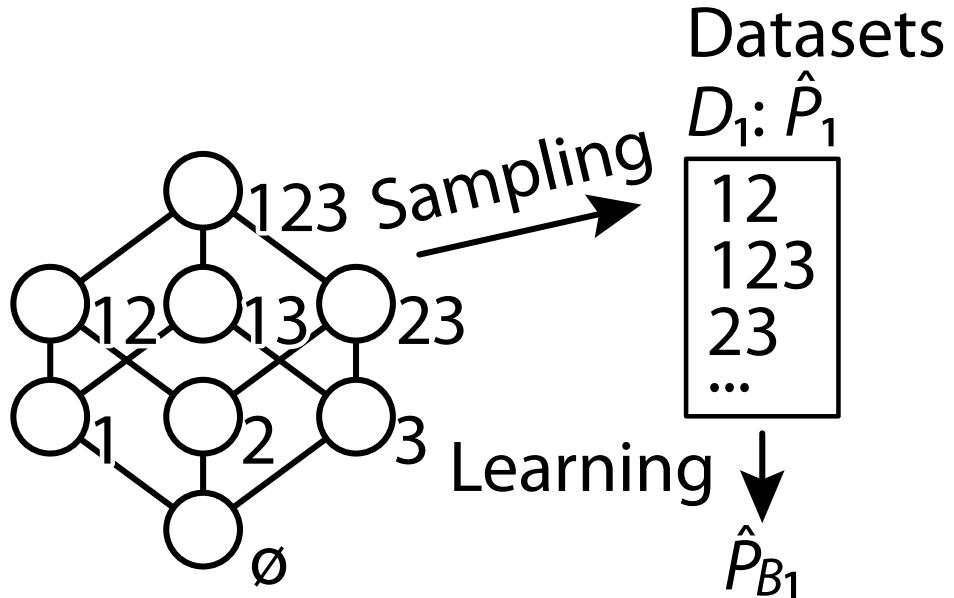
Outcome
space



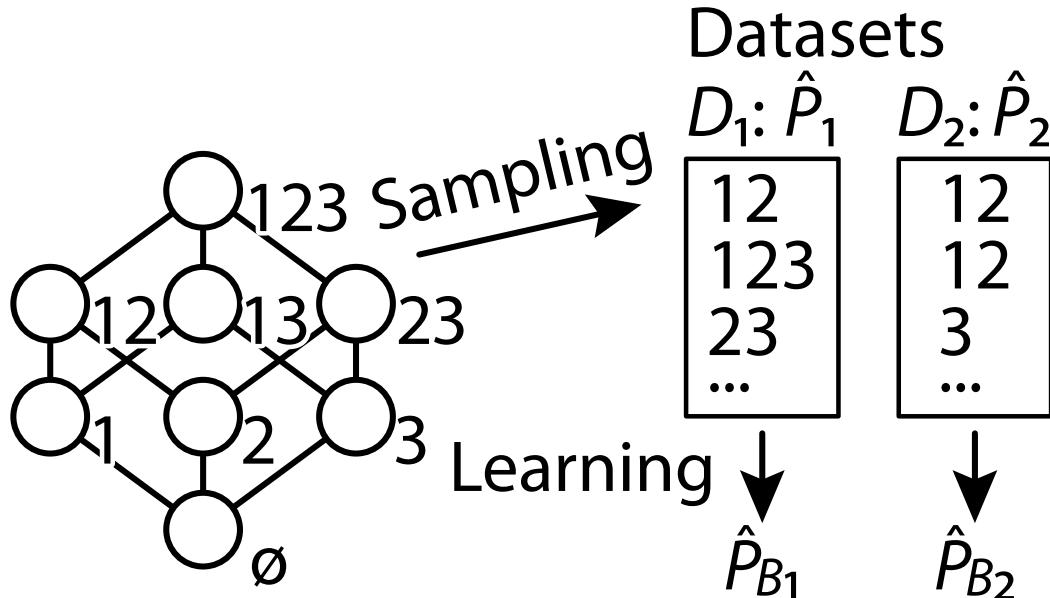
Deep Boltzmann Machines (DBMs)



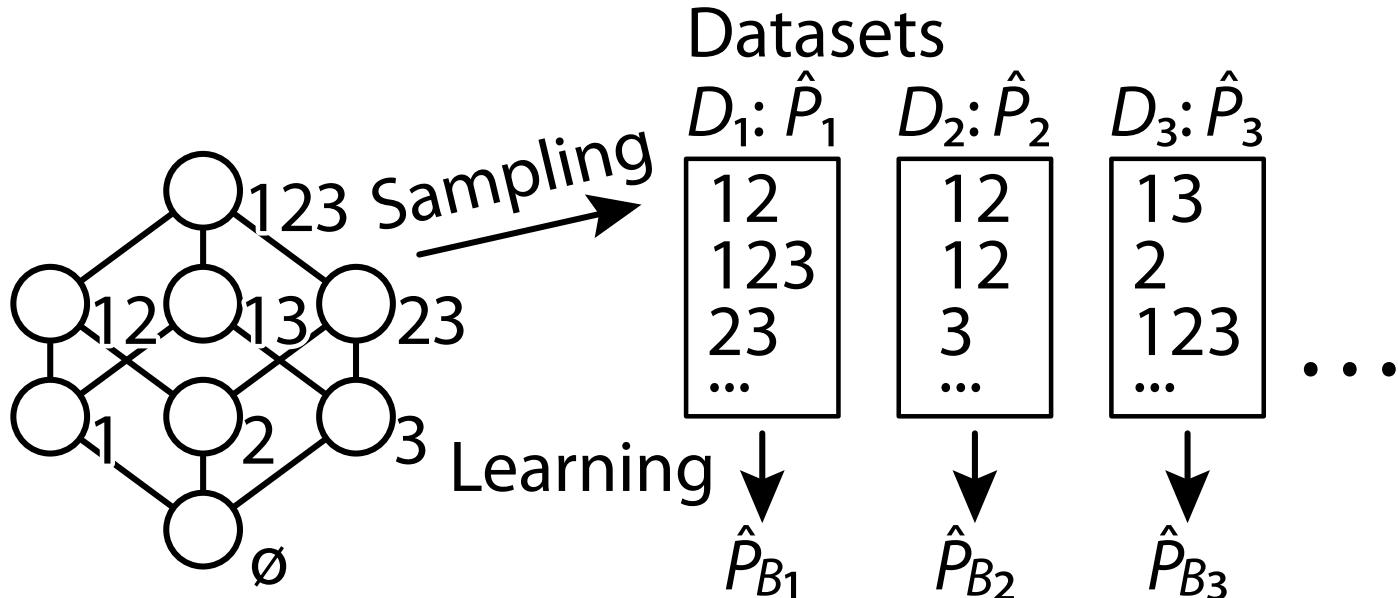
Learning from Data



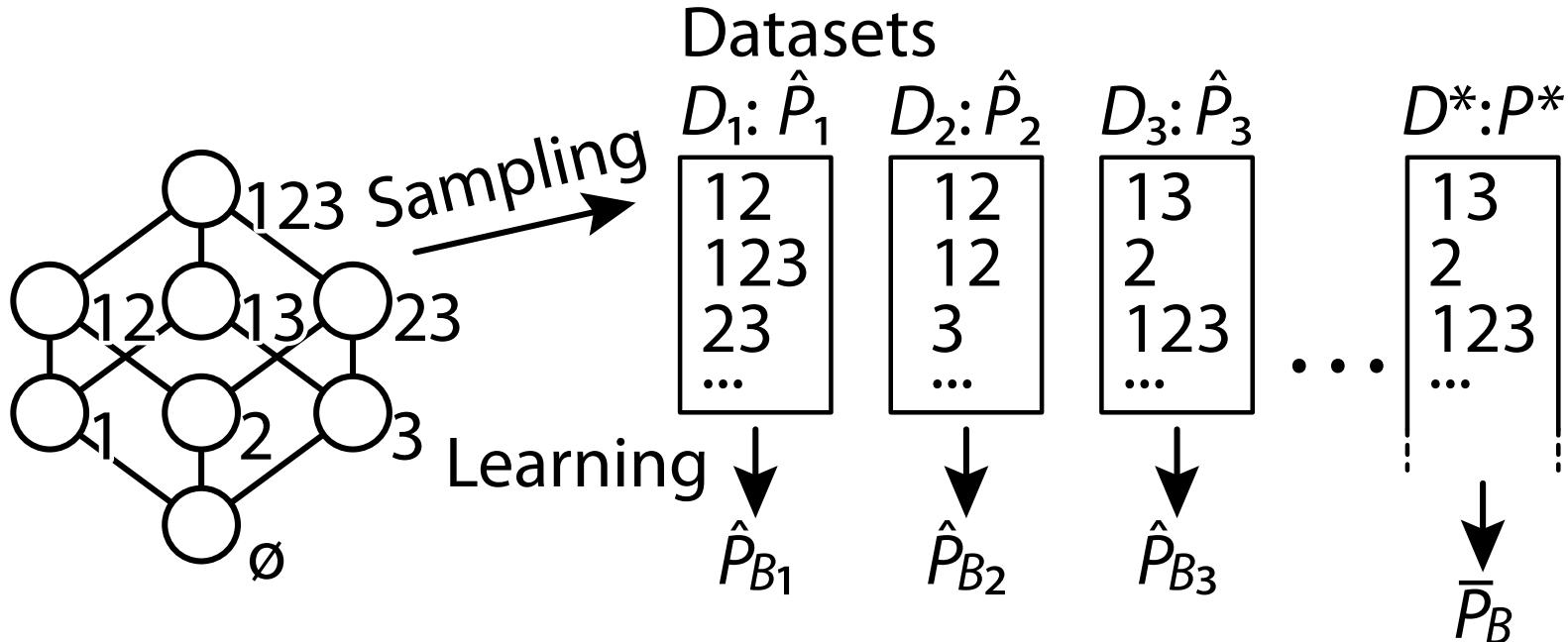
Learning from Data



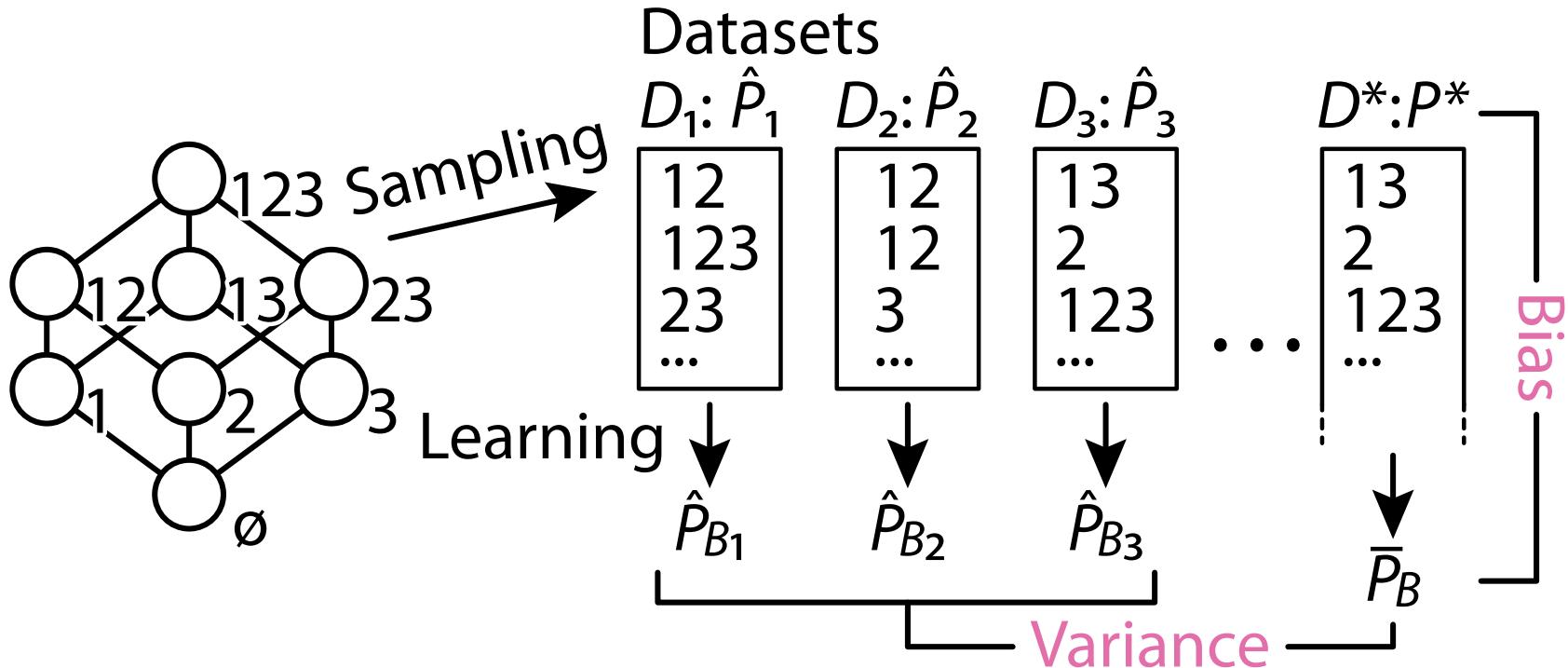
Learning from Data



Learning from Data



Learning from Data



Bias-Variance Tradeoff

- Bias = $D_{\text{KL}}(P^*, \bar{P}_B)$
- Variance = $\mathbf{E}[D_{\text{KL}}(\bar{P}_B, \hat{P}_B)]$
- If we include more parameters in B :
 - Bias will **decrease**
 - Variance will **increase**
- Two extreme cases:
 - If $B = 2^V$, then $\hat{P}_B = \hat{P}$, thus bias = 0 but variance will be large
 - If $B = \emptyset$, \hat{P}_B is always the uniform distribution U , thus bias = $D_{\text{KL}}(U, P^*)$ and variance = 0

Bias-Variance Decomposition

- Decomposition of **MSE** (Mean Squared Error)

$$\begin{aligned}\mathbf{E}[(\hat{\theta} - \theta^*)^2] &= (\bar{\theta} - \theta^*)^2 + \mathbf{E}[(\hat{\theta} - \bar{\theta})^2] \\ &= \text{bias}^2(\hat{\theta}) + \text{var}[\hat{\theta}]\end{aligned}$$

$$\text{MSE} = \text{bias}^2 + \text{variance}$$

- θ^* : the true parameter
- $\hat{\theta}$: the estimate
- $\bar{\theta}$: the expected value of the estimate, $\bar{\theta} = \mathbf{E}[\hat{\theta}]$
(the estimate obtained from infinitely many data points)
- The expectation **E** is about the true distribution $p(D; \theta^*)$

Example: Gaussian Mean Estimation

- Estimate the **mean** from N data points x_1, x_2, \dots, x_N sampled from a Gaussian distribution $N(\theta^* = 1, \sigma^2)$
- Strategy 1: MLE

$$\text{bias} = \mathbf{E}[\hat{\theta}] - \theta^* = \mathbf{E}\left[\frac{1}{N} \sum_{i=1}^N x_i\right] - \theta^* = N\theta^*/N - \theta^* = 0$$

$$\text{variance} = \sigma^2/N$$

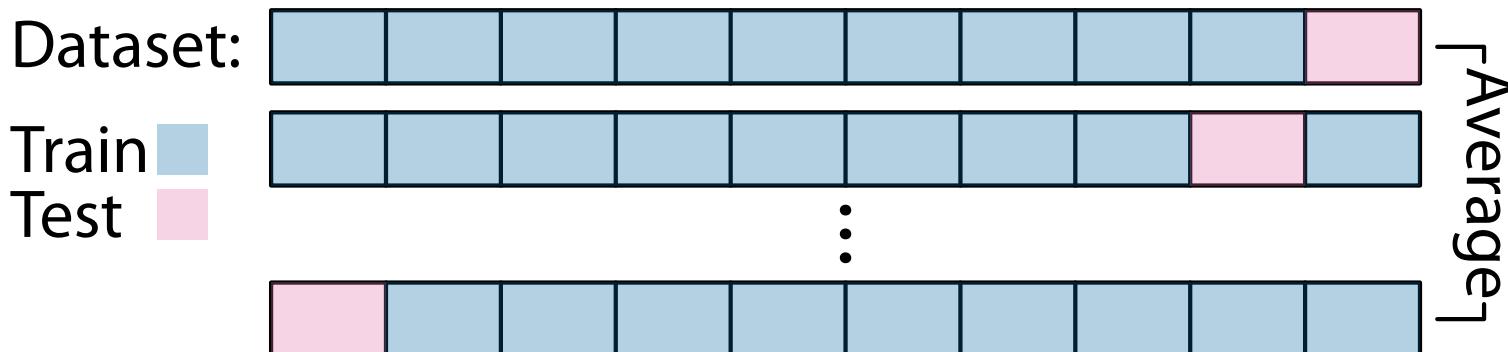
- Strategy 2: MAP estimate with a prior $N(\theta_0, \sigma^2/\kappa_0)$

$$\text{bias} = \left(w\mathbf{E}[\hat{\theta}] + (1-w)\theta_0\right) - \theta^* = (1-w)(\theta_0 - \theta^*), \quad w = N/(N + \kappa_0),$$

$$\text{variance} = w^2\sigma^2/N$$

Practical Solution: Cross-Validation

- CV (Cross Validation) is the most convenient way to find the best parameter from data without seeing the true parameter
- K-fold cross-validation is typically used



Fisher Information

- Let $p(x; \xi)$ be a distribution with a parameter ξ
- The Fisher information $g(\xi)$ of ξ is

$$g(\xi) = \mathbf{E} \left[\left(\frac{\partial}{\partial \xi} \log p(x; \xi) \right)^2 \right] = \sum_{x \in S} p(x; \xi) \left(\frac{\partial}{\partial \xi} \log p(x; \xi) \right)^2$$

- If there are multiple parameters $\boldsymbol{\xi} = (\xi_1, \xi_2, \dots, \xi_m)$, the Fisher information matrix is a $m \times m$ matrix $G(\xi)$ given as

$$g(\boldsymbol{\xi})_{ij} = \mathbf{E} \left[\frac{\partial}{\partial \xi_i} \log p(x; \xi) \frac{\partial}{\partial \xi_j} \log p(x; \xi) \right]$$

Cramér-Rao Lower Bound

- Let $\boldsymbol{\xi}$ be **unbiased**: $\mathbf{E}[\hat{\boldsymbol{\xi}}] = \boldsymbol{\xi}^*$

- Cramér-Rao inequality**:

$$E \geq \frac{1}{N} G(\boldsymbol{\xi})^{-1}$$

where $E = (e_{ij})$, each $e_{ij} = \mathbf{E}[(\hat{\xi}_i - \xi_i^*)(\hat{\xi}_j - \xi_j^*)]$

- E coincides with the **covariance matrix**, $e_{ii} = \mathbf{E}[(\hat{\xi}_i - \xi_i^*)^2] = \text{var}(\hat{\xi}_i)$
- $A > B$ if $A - B$ is positive definite
 - C is positive definite if $\mathbf{x}^T C \mathbf{x} > 0$ for any non-zero $\mathbf{x} \in \mathbb{R}^n$
- In MLE, $E \rightarrow (1/N)G(\boldsymbol{\xi})^{-1}$ when $N \rightarrow \infty$

Example in Gaussian Mean Estimation

- Estimate the **mean** from N data points x_1, x_2, \dots, x_N sampled from a Gaussian distribution $N(\theta^*, \sigma^2)$
- Fisher information:

$$g(\theta) = \frac{1}{\sigma^2}$$

- Cramér-Rao bound:

$$\text{var}[\hat{\theta}] \geq \frac{\sigma^2}{N}$$

- In this case, $\text{var}[\hat{\theta}] = \sigma^2/N$ always holds

Model Selection by AIC

- The **AIC** (Akaike information criterion) is one of the most famous measure of the quality of statistical models

$$\text{AIC} = -2I(D) + 2k$$

- $I(D)$ is the maximized log-likelihood
 - k is the number of parameters

- This cannot be directly used for log-linear models on posets as it is a hierarchical model with including higher-order associations
 - It is still under development...